

Timing: Precision Beam Timing

FAC Meeting Nov 12, 2008

Timing Requirements

- For pump / probe experiments need to synchronize experimenters' lasers to the X-rays
 - Want timing stability < RMS pulse width
 - 30 femtosecond RMS (normal operation)
 - Could need 2 femtoseconds in ultra-short bunch mode (Discussed today breakout 1,2 15:20)
- Time-constant for drift is “scan time” in experiment (seconds to days???)

System Components

- Phase distribution system
 - LBNL phase stabilized fiber system
- Beam phase reference
 - Original plan to use electro-optical system
 - Decision to use phase cavity
- X-ray timing
 - Not perfectly locked to the electron beam time
 - Hope for future direct optical – to – X-ray timing.

LBNL Fiber System

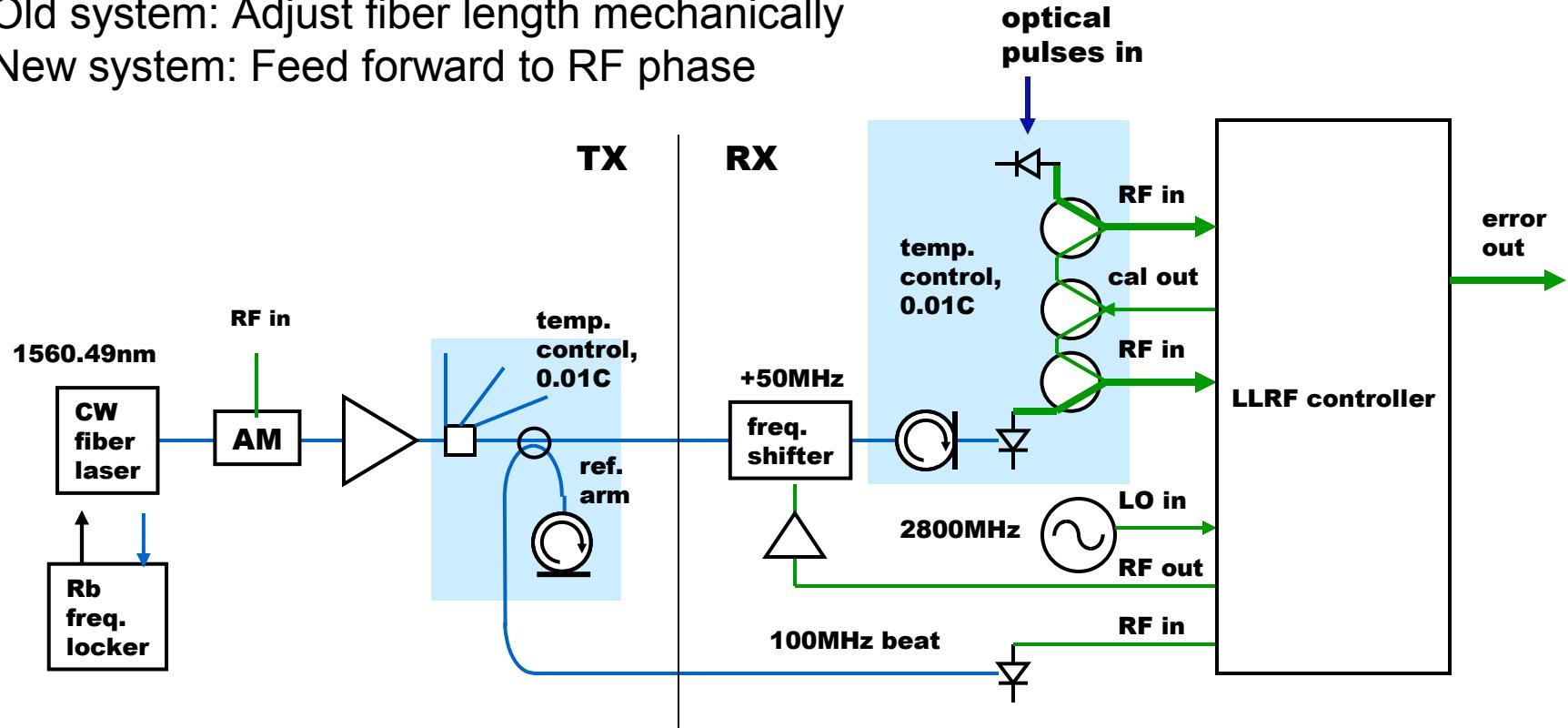
- Stabilized fiber link:
 - Measure optical fringes in fiber
 - Shift phase of RF to compensate for measured changes in fiber length
- Specified at <100 femtosecond drift
 - Expect much better
- Different technology than DESY or NLC systems.

LBNL Fiber System

Measure fiber length interferometrically

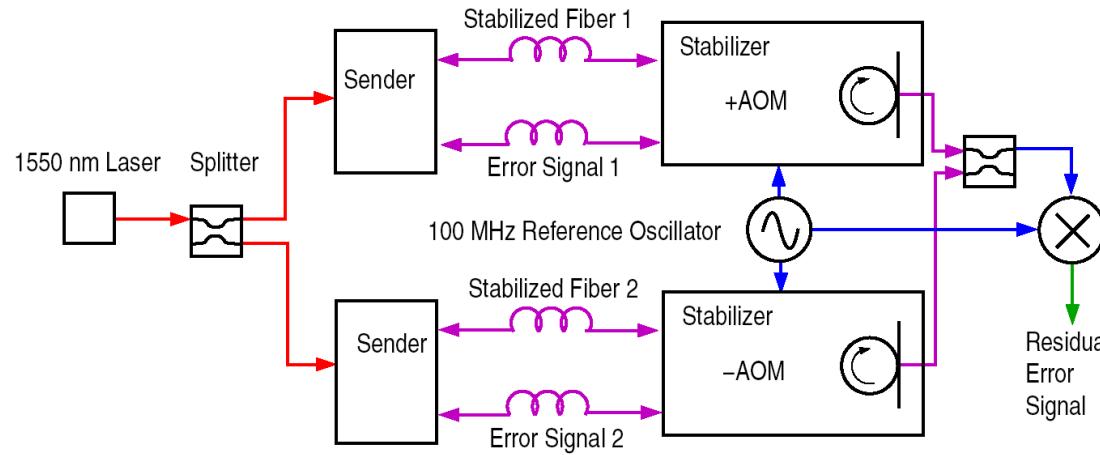
Old system: Adjust fiber length mechanically

New system: Feed forward to RF phase



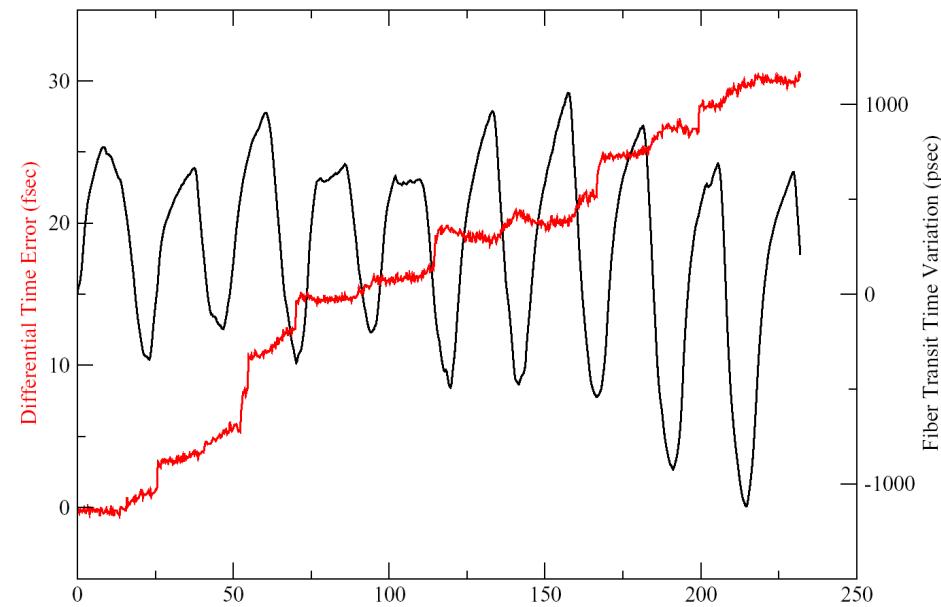
LBNL Test System

- 2, 2.8 Kilometer links in SLAC klystron Gallery
- Independently stabilize links, compare errors



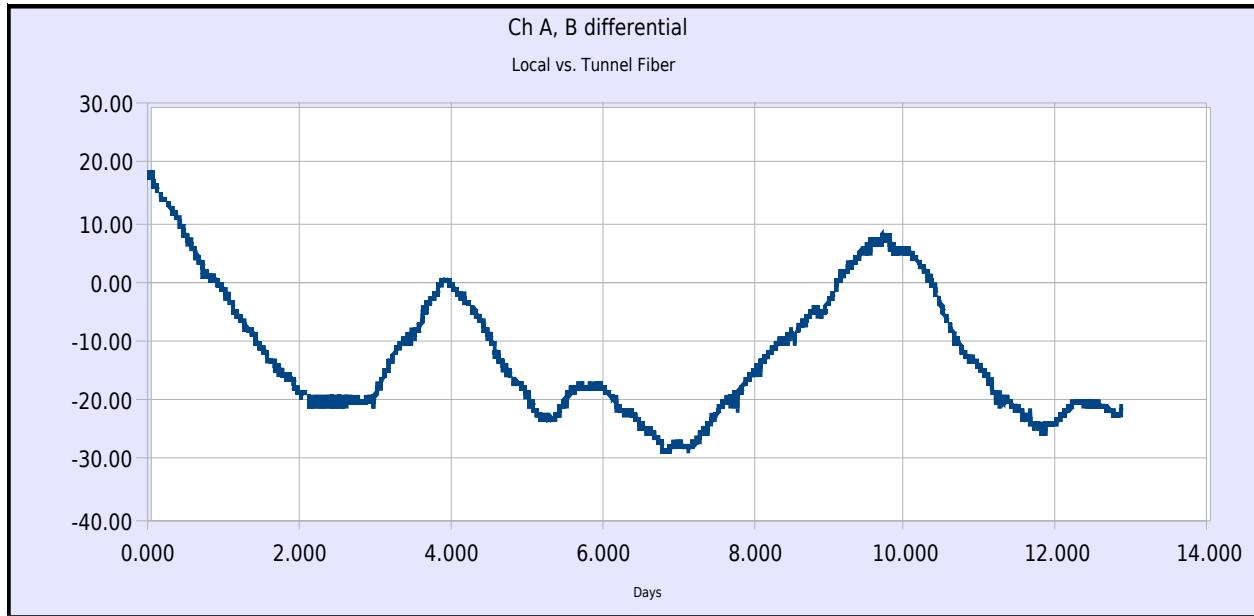
Test in SLAC Klystron Gallery

- 225 hour run
- Correcting fiber length change of ~ 1 nanosecond.
- Residual phase change ~20 fsec



Reference Arm Stability - Humidity

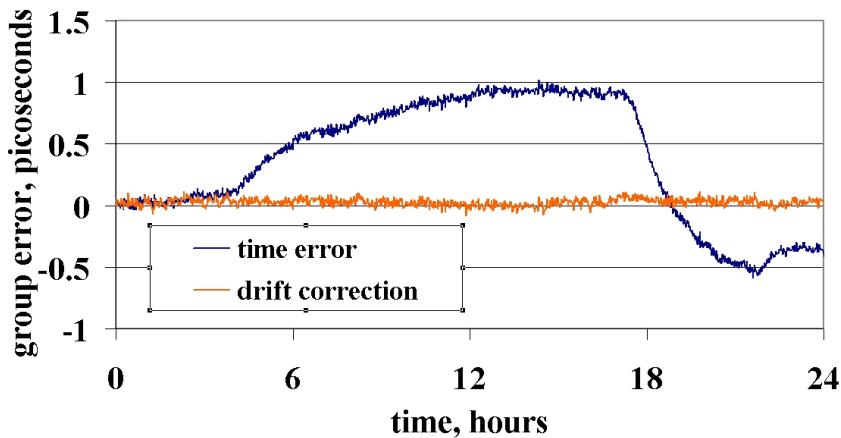
- Interferometer reference arm stability for temperature and humidity
- 50 femtosecond variation



Delay variation in
femtoseconds
with humidity
changes

Group Delay

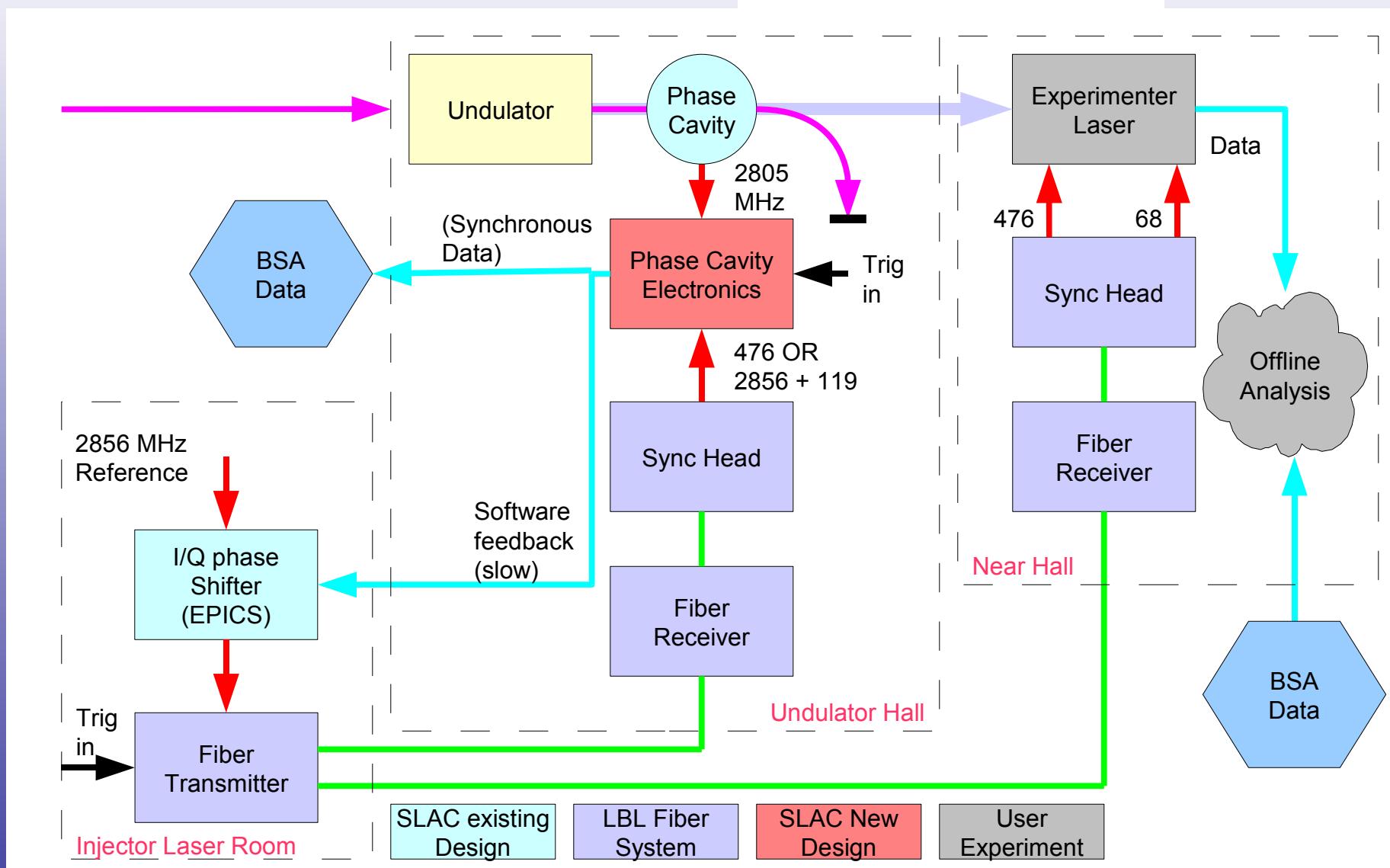
- Interferometer fixes optical carrier, not RF modulated signal
- Fairly big effect: ~ 1 picosecond in test
- Size of effect known – fix in feedforward
- 36 femtosecond RMS achieved.



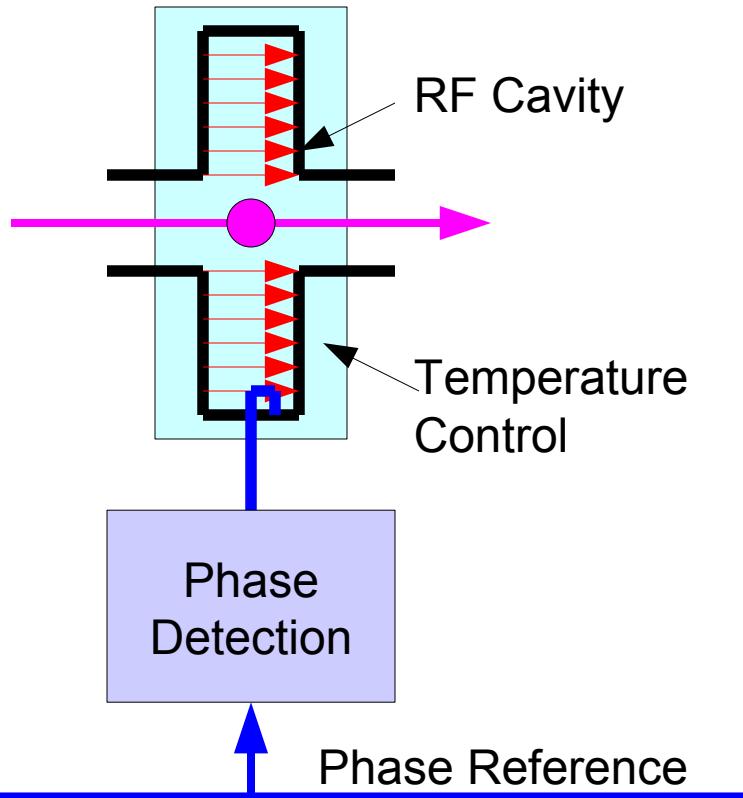
With and without group delay
correction

AM to PM Conversion in Photodiode

- Need to connect “ugly” RF to “perfect” optical system.
- Photodiodes have phase delay dependent on optical power -> drift.
- Can select operating power so that there is no first order variation
- For 10% laser power variation, get 10 femtoseconds drift: OK

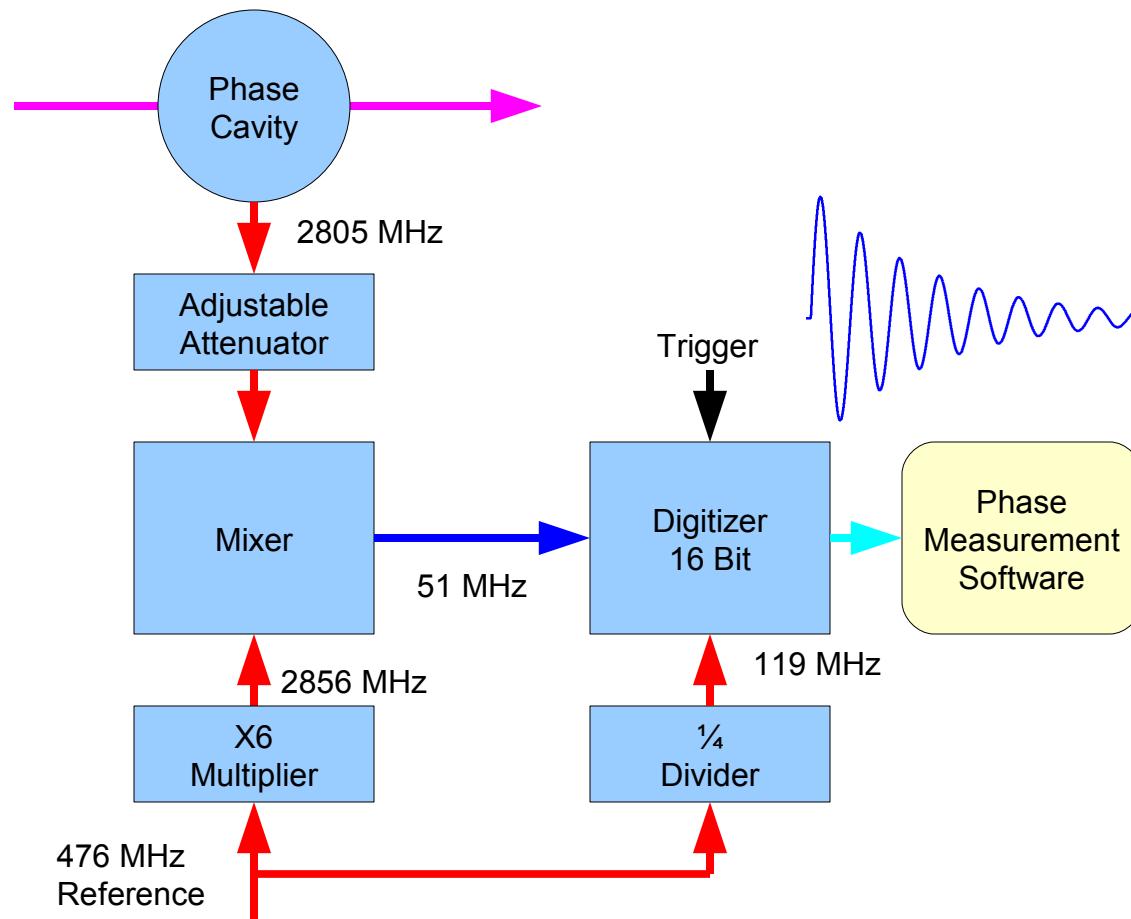


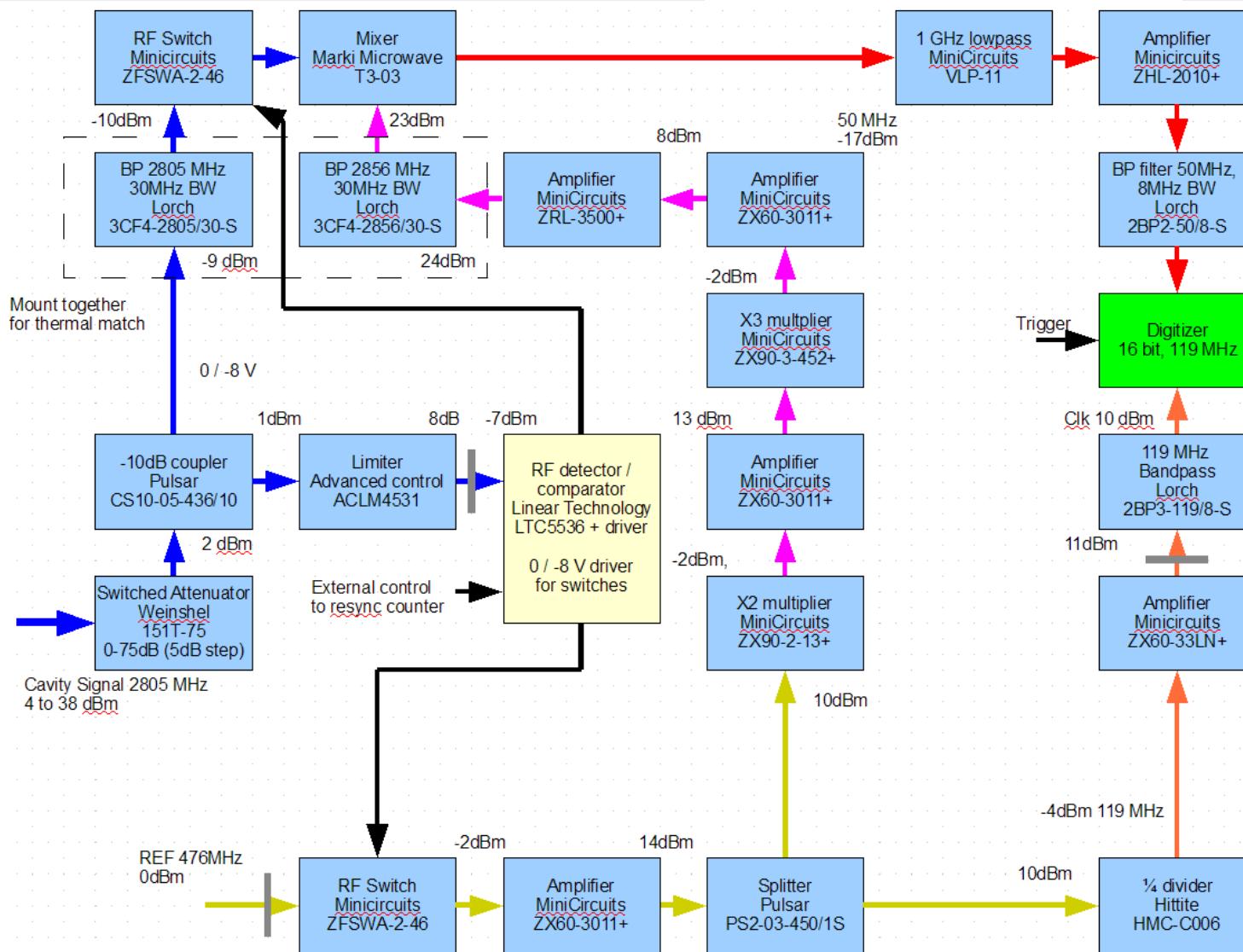
Phase Cavity



- Energy deposited by beam is large
 - Noise is insignificant
- High Q reduces peak power seen by electronics
 - Reduce non-linear amplitude → phase
- Increases drift

Block Diagram of Phase Cavity System





Phase Cavity Noise Sources

■ Electronic Noise:

- < 10 attoseconds thermal noise
- Amplitude to phase conversion → Limit signal levels to maintain electronics linearity.
- **Digitizer noise:** 16 bit (14 effective) 119MHz digitizer. Need to scale signal correctly
- Result is < 1 femtosecond RMS.

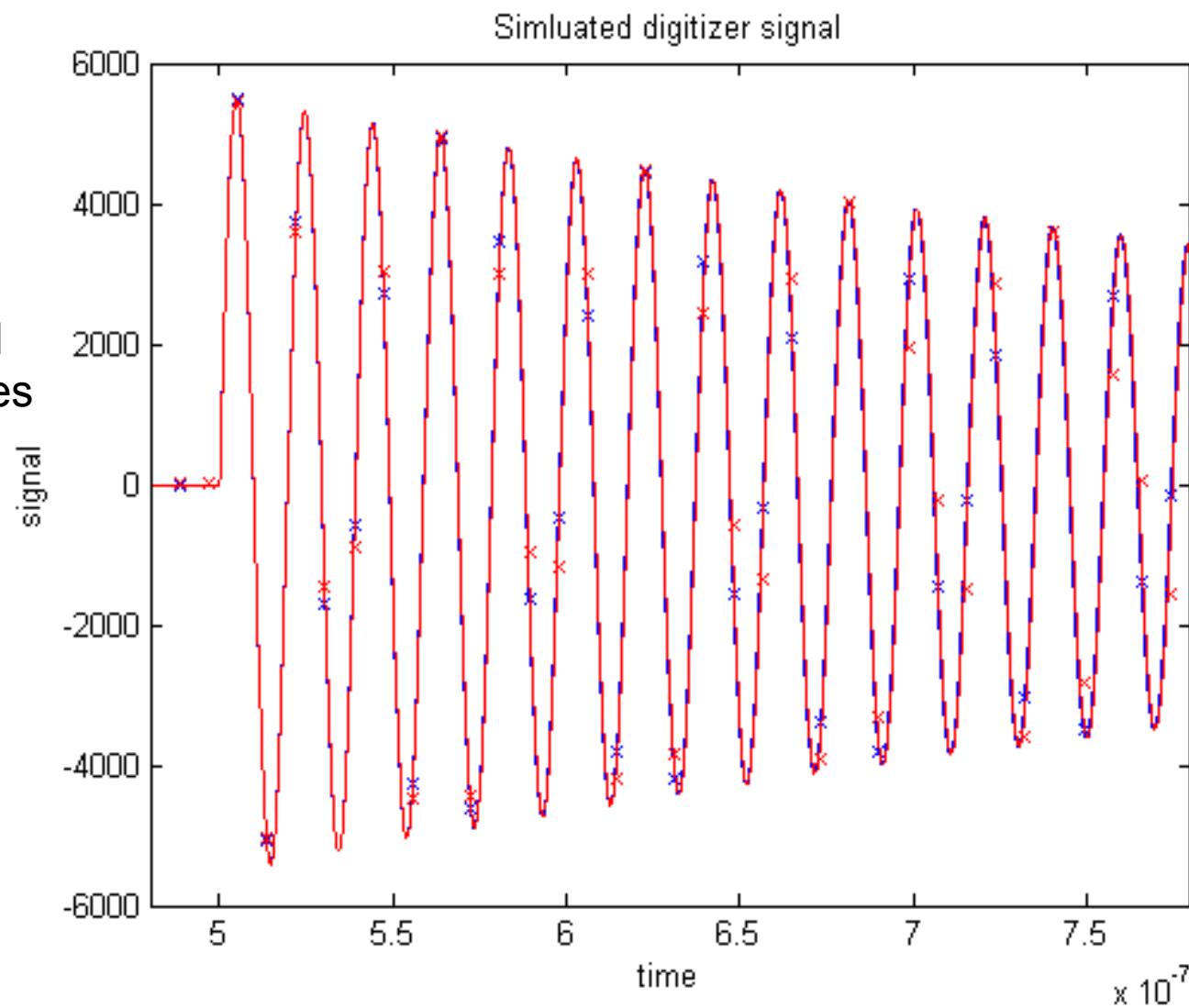
■ Reference phase noise:

- Assume 476 MHz oscillator -150dBC/Hz from 10-200KHz. : 5 femtoseconds RMS

Phase Cavity Phase Drifts

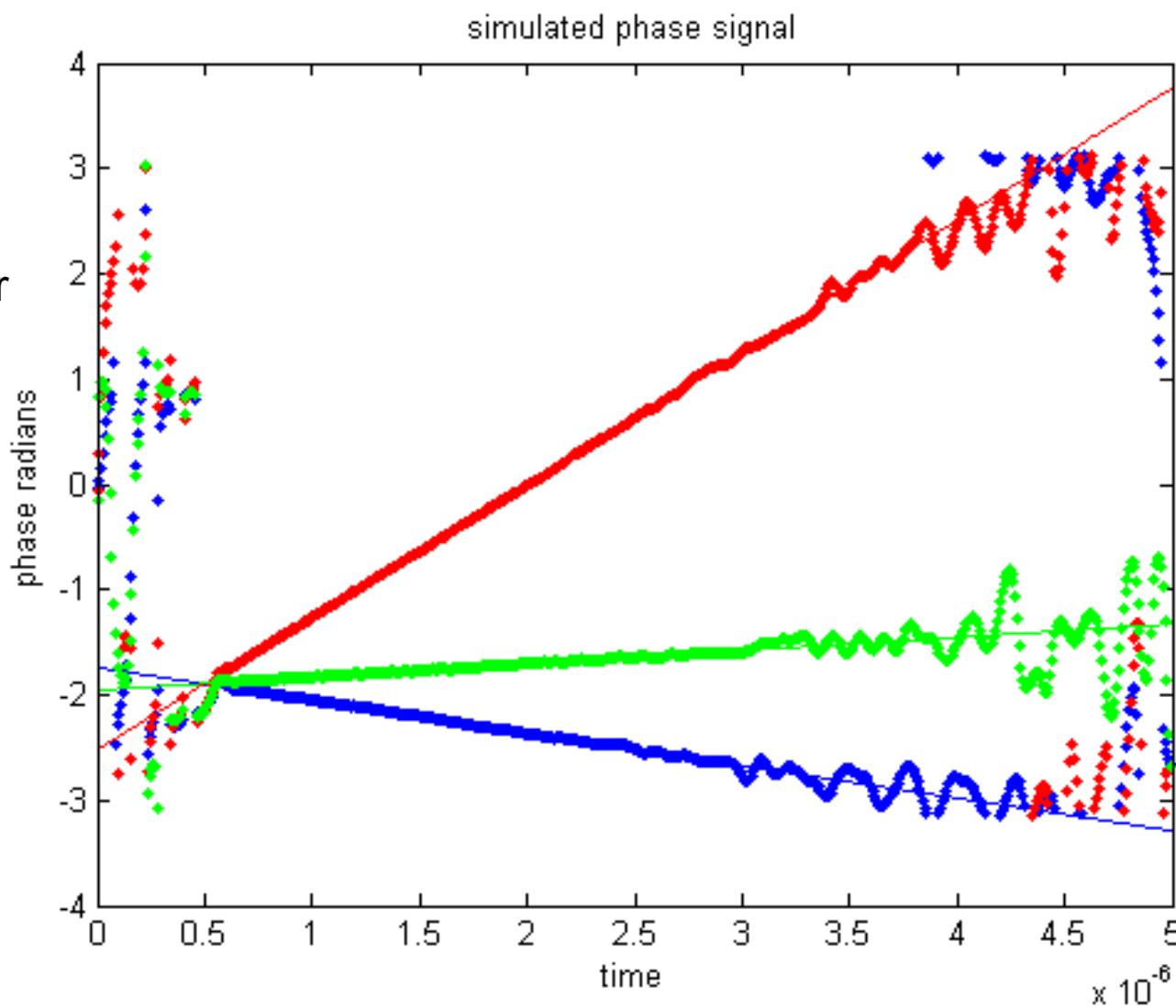
- Cavity frequency drifts $1.6 \times 10^{-5} / \text{C}^\circ$.
 - 0.1 C° temperature change \rightarrow 300 femtoseconds
 - Need temperature correction algorithm
- Cable drifts:
 - Use short (2M), temperature compensated cables
 - Estimate phase drift <2 fsec for 0.1 C°
- Electronics drift:
 - Filter delays compensated.
 - Component drifts not specified

Simulated IF
waveforms and
digitizer samples
for 2 different
cavity
temperatures



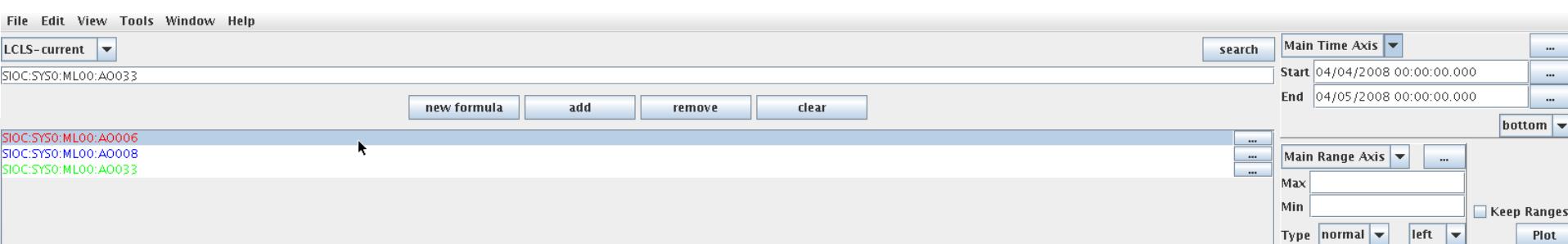
Cavity phase for
3 different
temperatures.

Note crossing
point.

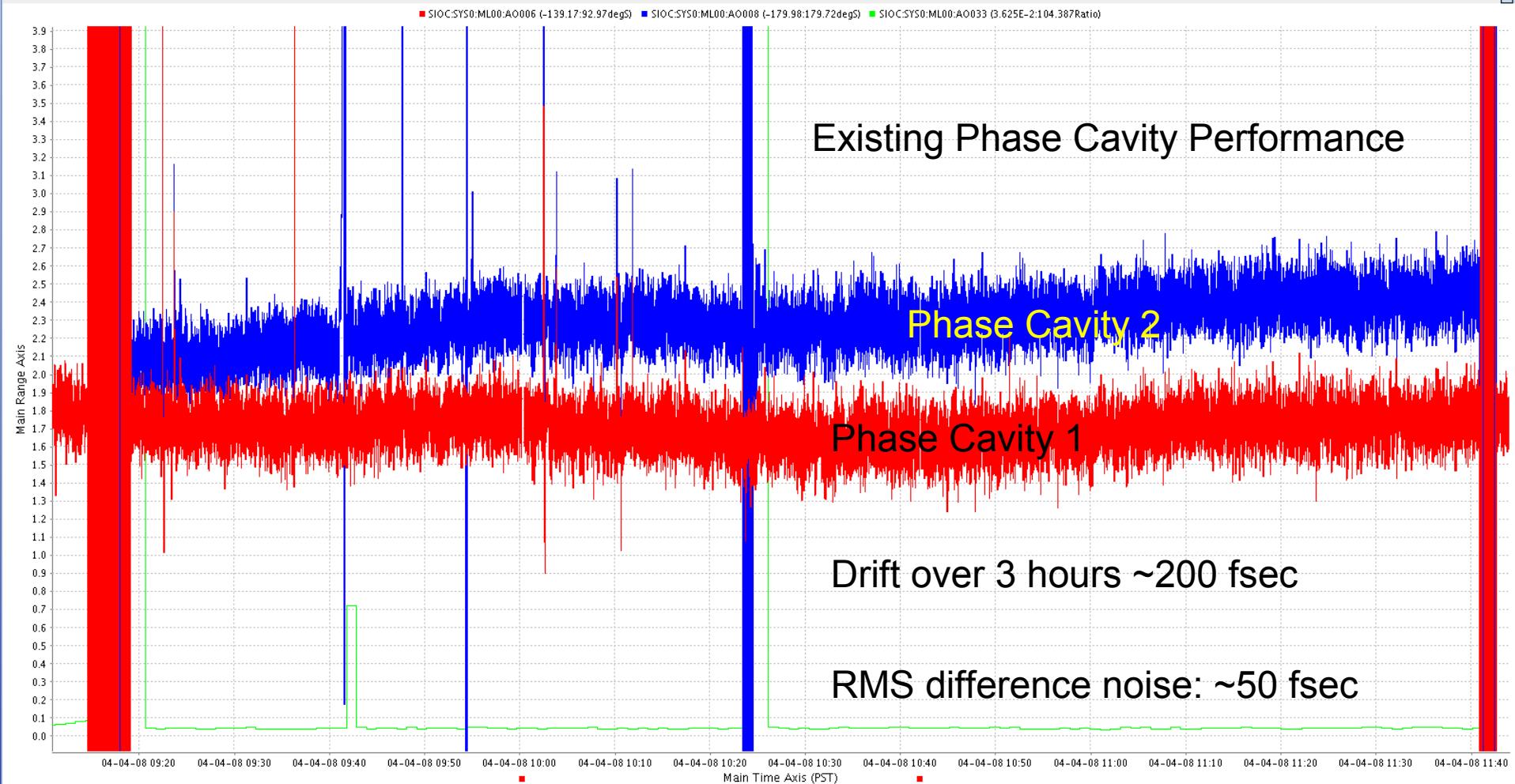


Existing Phase Cavities

- Use same 2805 MHz phase cavity design as new system.
- Use existing LLRF phase measurement hardware
 - Simple, but no programmable gain for bunch charge changes
- Performance still very good:



JFreeChart For Time Plots JFreeChart For Correlations JFreeChart For Waveforms



Temperature Compensation Algorithm

- Measure phase vs. time on each pulse
- Linear fit back to beam time.
 - Phase at beam time is independent of cavity temperature.
- With 10 nanosecond accuracy, can measure phase to ~ 10 femtoseconds (for 0.1 C°)
- With 2 cavities, can change temperature to find effective arrival time to $< 1\text{nsec}$
 - Should give \sim femtosecond stability.

Expected Phase Cavity Performance

- High confidence noise and drift < 100 femtoseconds.
- Calculated short term noise 5 femtoseconds RMS.
- Known drift sources ~ 5 femtoseconds
 - Don't really believe this!!
- Build initial system and see what limits performance.

Status

■ BNL Fiber system

- Expect installation before first user experiments
- Can use non-stabilized system as fall-back

■ Phase Cavity

- Expect hardware ready by March.
- Slow software ready by user experiments
 - LCLS RMS jitter ~50 fsec RMS
- Pulse-to-pulse synchronous software later

■ Still thinking about X-ray timing