

LCLS Physics		
Requirements Document #	1.4 – 003	Undulator
		Revision 0
<u>Beam Based Alignment System Requirements</u>		
Paul Emma (Author)	_____	_____
	Signature	Date
Steve Milton (Undulator Manager)	_____	_____
	Signature	Date
Heinz-Dieter Nuhn (Undulator Physicist)	_____	_____
	Signature	Date
John Galayda (Project Director)	_____	_____
	Signature	Date

Brief Summary: This document summarizes the undulator system requirements necessary to support successful beam-based alignment of the undulator trajectory..

Keywords: Undulator, RF Cavity BPM, Beam Based Alignment

Key WBS#'s: 1.4

Beam-Based Alignment System Requirements

The electron trajectory through the FEL undulator must be straight to a level of about 2 microns over one FEL gain length (~5 m). This level is difficult to achieve using standard component survey methods, and therefore requires a special electron beam-based alignment algorithm which samples undulator BPM readings at three different beam energies (14, 7, and 4.5 GeV).

Detailed simulations have been made which indicate that adequate beam-based alignment can be achieved if specific undulator systems are constructed, and beam stability is within, tight tolerance specifications. Table 1 summarizes these specifications for the most critical parameters, while Fig. 1 shows the simulated x and y trajectories after 3 passes of the beam-based alignment (BBA) procedure, under the conditions shown in Table 1.

Table 1: Undulator and beam specifications for the most critical parameters (quadrupole magnet gradient is 60 T/m with mean quadrupole spacing of ~3.9-m).

Parameter Description	Value	Unit
Maximum BPM rms position resolution (x and y)	1	μm
Quadrupole magnet-mover x and y positioning repeatability	± 2	μm
Initial rms uncorrelated quad and BPM alignment	100	μm
Initial rms correlated quad and BPM alignment	300	μm
Maximum BPM mean and rms calibration error	10, 3	%
Maximum quadrupole mean and rms gradient error	0.3, 0.3	%
Maximum quadrupole-mover mean and rms calibration error	5, 3	%
Maximum random rms undulator pole field errors	0.05	%
Incoming rms shot-to-shot trajectory jitter (% of rms beam size)	<20	%
Maximum uncertainty in knowledge of beam energy	2	%
BPM absolute read-back rms stability over one hour	2	μm
Minimum quadrupole-mover dynamic range	± 500	μm
Earth's magnetic field compensated in undulator shimming	<0.05	G

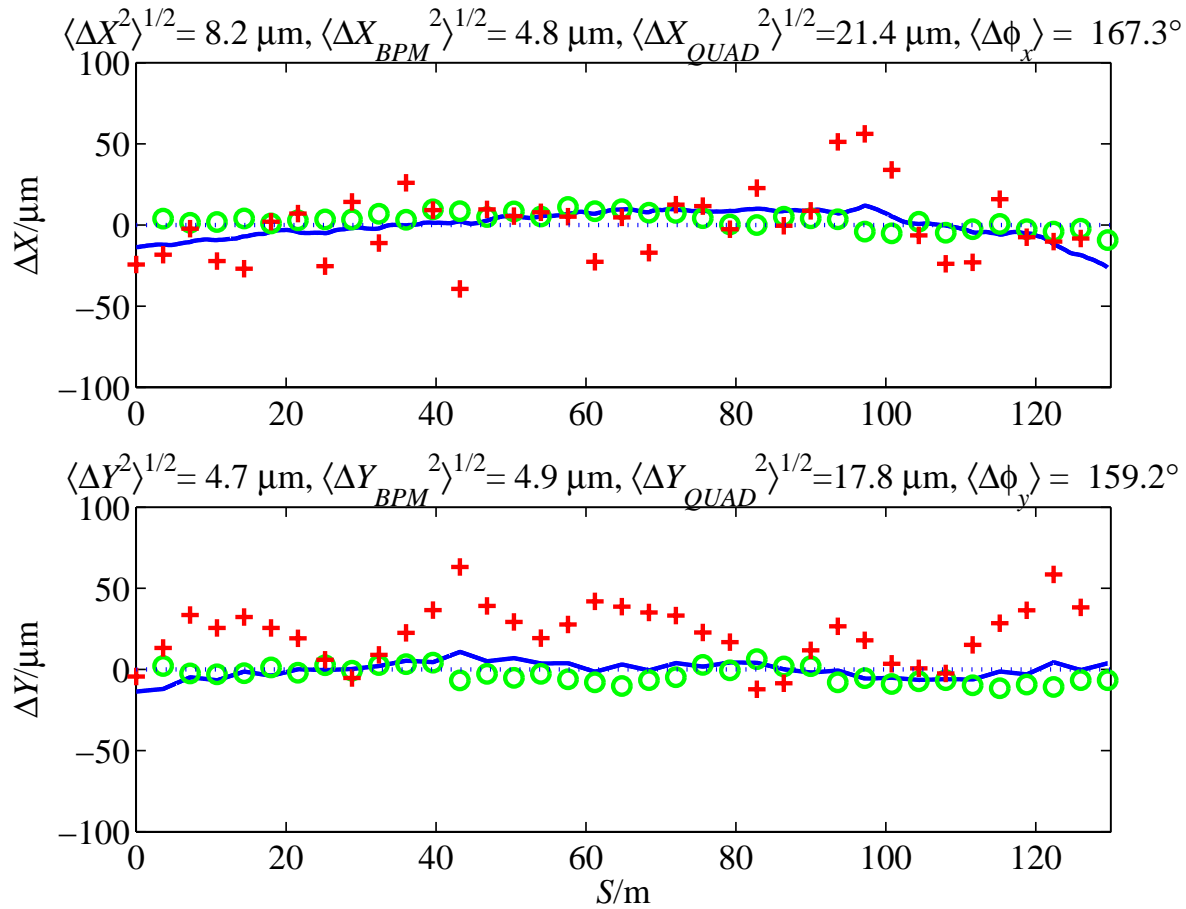


Fig. 1. Electron x and y trajectories through undulator at 14 GeV after 3 passes of the BBA procedure. The true trajectory is in solid-blue ($8.2 \mu\text{m}$ and $4.7 \mu\text{m}$), the BPM read-backs are green-circles ($4.8 \mu\text{m}$ and $4.9 \mu\text{m}$), and the final quadrupole centers are red-plus-signs ($21.4 \mu\text{m}$ and $17.8 \mu\text{m}$). The total phase error at 1.5 \AA is $<330^\circ$.